

ASSEMBLY & INSTRUCTION MANUAL



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Introduction

The mechanical coding wheel is the heart of the Mech.5 Mechanical Coding Robot. It steers its coded courses and programmed tasks. Coding is executed effortlessly by snapping the coding buttons onto the coding wheel directing your robot to perform its basic functions – move forward, backward, right or left, spin or pause. Thanks to this simple to follow approach, coding and performing more challenging tasks like throwing, lifting, kicking or drawing, become achievable as the user's coding skills increase.

This mission-based, entry level STEM coding robot is designed to inspire users to learn about mechanical engineering principles and coding basics. It encourages children to think while also developing their problem-solving and troubleshooting skills when faced with different tasks and difficulties. Engage in the coding world and beyond by challenging yourself with your very first coding robot.



	(CAL)	2				1		2
P12	P12 Battery Holder with Connector				P13		Motor with PC Board	
DC :	3V = = =			QTY				QTY
				1				

1

Plastic Parts





Remove burrs



Some parts may look quite similar. They should be assembled in the designated direction and position shown in manual.



Coding buttons can be removed for new programming. Remove them straight up off the coding wheel. Do not torque them to avoid damage.



Head Module Assembly







Rear Gear Box Testing (1)













Accessory Module Assembly



About the Coding Wheel



How to Install Coding Buttons



How to Install the Coding Wheel







How the Coding Buttons Work







Drawing-bot Assembly







To better understand the assembly and operations of each project, view the sample video listed in Video Tips on the project page.



Forklift-bot Assembly







Trouble Shooting

Check the coding buttons and wheel installation, refer to pages 14-15
See page 37

Throwing-bot Assembly







Gripper-bot Assembly







Soccer-bot Assembly







i How to Replace the Batteries



Trouble Shooting

- 1. Ensure all coding buttons are assembled correctly (refer to page 14).
- 2. Ensure the coding wheel is assembled correctly (refer to pages 15-17, steps 1-6).
- 3. If the robot does not move smoothly or appropriately when turning right/left or stopping, please go back to pages 9–10 and ensure steps 18 21 are correctly executed.
- 4. If the robot does not move smoothly or appropriately when going backward, please go back to page 6 step **7** to check if parts **B5**, **B7**, and **D12** are assembled in the right way.
- 5. If the Drawing-bot does not follow the coding program correctly, please go back to page 21 step 2 to check if parts D3 and C15 are assembled in the right way.
- 6. If the Forklift-bot does not follow the coding program correctly, please go back to page 26 to check if part **E5** is assembled in the right way.
- If the Throwing-bot does not follow the coding program correctly, please go back to page 17 step 5 to check if parts E21 and E22 are assembled in the right way.
- 8. If the Gripper-bot does not follow the coding program correctly, please go back to page 31 step 5 to check if part C16 is assembled in the right way.
- 9. If the Soccer-bot does not follow the coding program correctly, please go back to page 34 step 4 to check if part C16 is assembled in the right way.





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Printed in Taiwan

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