EXPERIMENT MANUAL

MY ROBOTIC PET TUMBLING HEDGEHOG

LET'S GET Rolling!

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>>> SAFETY INFORMATION

Dear Parents and Adults,

Before building and experimenting, read the instructions together with your child and discuss the safety instructions. Please provide your child with the help and advice that he or she needs for tricky assembly steps and experiments, and accompany him or her every step of the way.

Should your child work on a table, give them a table mat to prevent damaging the furniture.

When cutting the plastic parts with a cutter, special care must be taken to avoid sharp edges, rough edges, and burrs. These can be removed using a cutter and a file. Provide your child with a cutter and supervise him or her until you are sure that he or she can use it without supervision.

We wish you and your child a lot of fun with the Tumbling Hedgehog!

Warning. Not suitable for children under 3 years. Choking hazard — small parts may be swallowed or inhaled.

Keep the packaging and instructions as they contain important information.

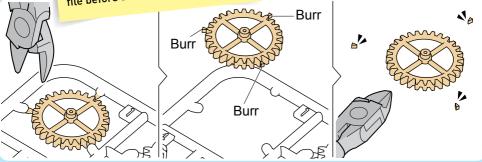
Only for use by children from 7 years or older. Instructions for parents or other responsible persons are included and must be observed.

NOTES ON ENVIRONMENTAL **PROTECTION/NOTES ON DISPOSAL** OF ELECTRICAL AND ELECTRONIC **COMPONENTS:**

The electronic components of this product are recyclable. For the sake of the environment, do not throw them into the household trash at the end of their lifespan. They must be delivered to a collection location for electronic waste, as indicated by the following symbol:



Please contact your local authorities for the appropriate disposal location.



IMPORTANT!

Remove the parts from the plastic molds only when they are needed. Remove excess material and burrs using a cutter and a nail file before assembly.

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TIP!

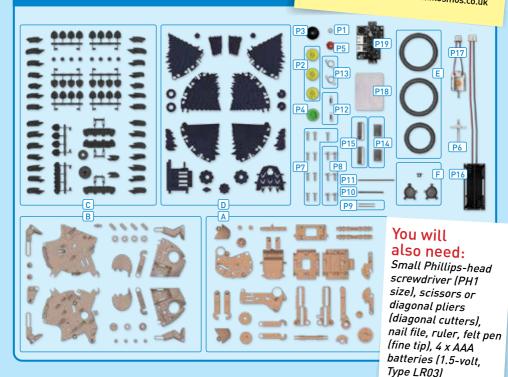
Additional information can be found in the Check It Out section on page 40.

>>> KIT CONTENTS

GOOD TO KNOW!

If you are missing any parts, please contact Thames & Kosmos customer service. US: techsupport@thamesandkosmos.com UK: techsupport@thamesandkosmos.co.uk

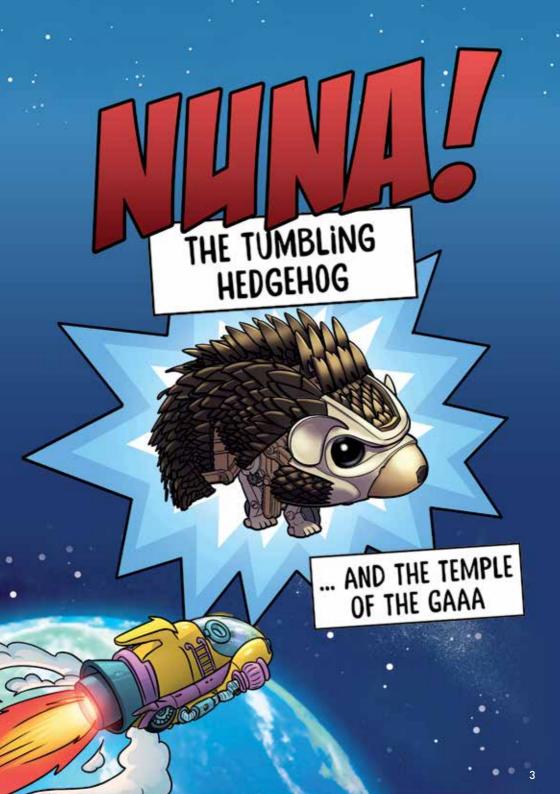
What's inside your experiment kit:



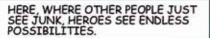
Checklist: Find — Inspect — Check Off

~	No.	Description	Quantity
0	P1	Small gear, white	1
0	P2	Gear, yellow	3
0	P3	Gear, black	1
0	P4	Gear, green	1
0	P5	Gear, red	1
0	P6	Gear with metal shaft	1
0	P7	Screw	9
0	P8	Wide head screw	6
0	P9	Round metal shaft	2
0	P10	Hexagonal metal shaft short	1
0	P11	Hexagonal metal shaft long	1
0	P12	Main spring	2
0	P13	Torsion spring	2

~	No.	Description Quar	ntity
0	P14	Metal block	2
0	P15	Metal cylinder	2
0	P16	Battery compartment	
		with connection cable	1
0	P17	Motor with connection cable	1
0	P18	2 Flexible connectors (+2 as spare parts)	2
0	P19	Circuit board	1
0	Α	Plastic parts group A with parts A1 – A27	1
0	в	Plastic parts group B with parts B1 – B21	1
0	С	Plastic parts group C with parts C1 – C37	1
0	D	Plastic parts group D with parts D1 – D20	1
0	Е	Plastic parts group E with parts E1 – E2	1
0	F	Plastic parts group F with parts F1 – F3	1



ANOTHER QUIET NIGHT IN THE JUNKYARD. EVERYONE IS ASLEEP EXCEPT TOM AND IZZY.





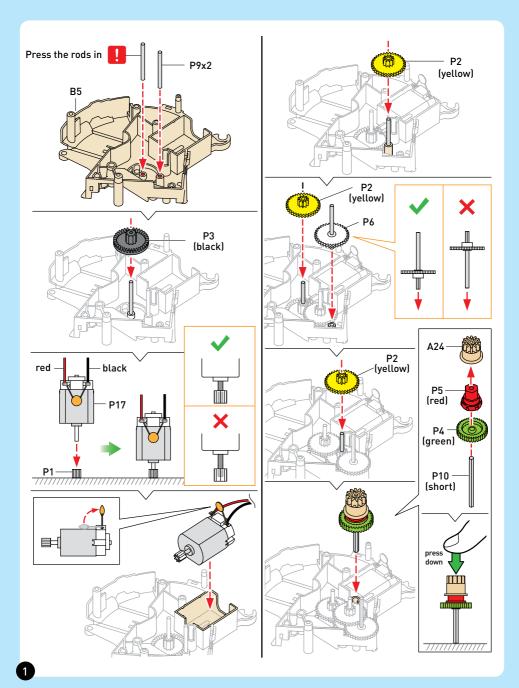
TOM & 1727

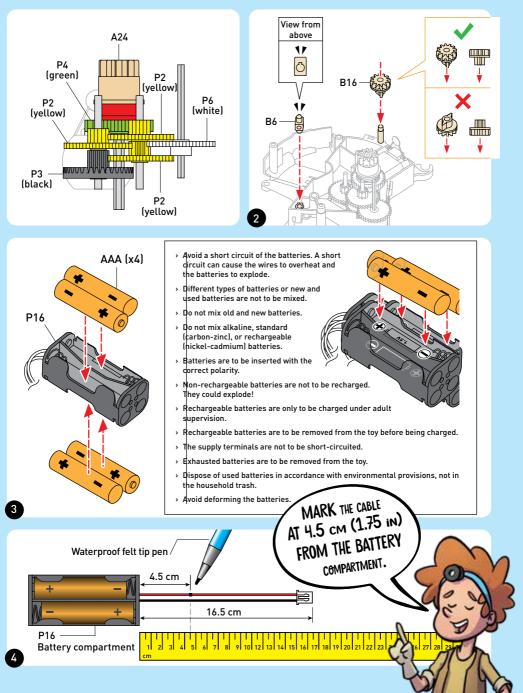


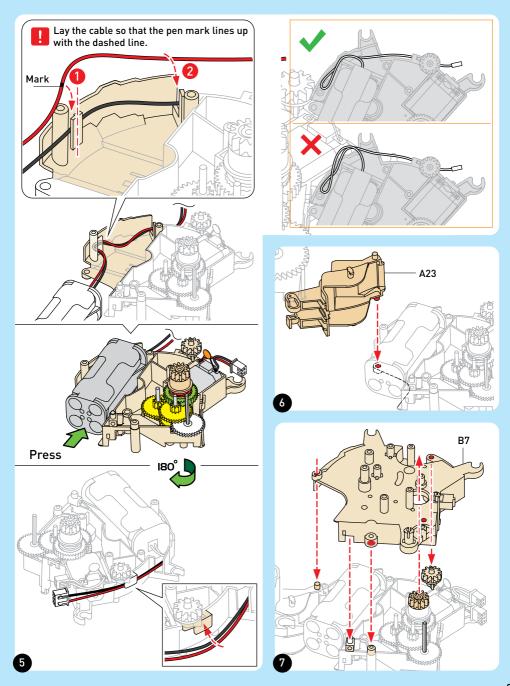




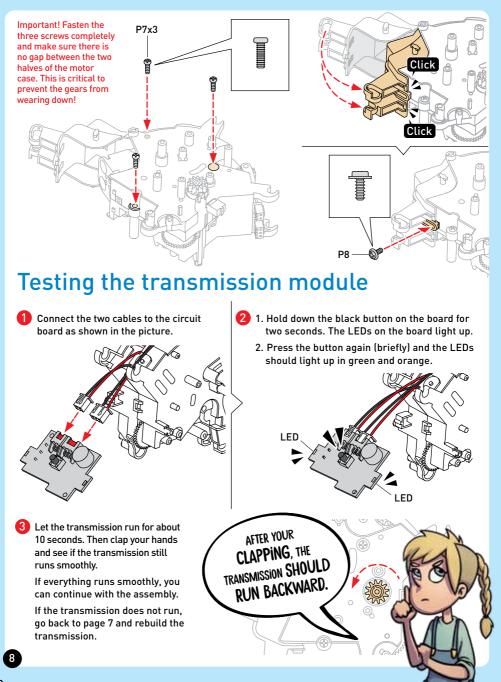
TRANSMISSION MODULE

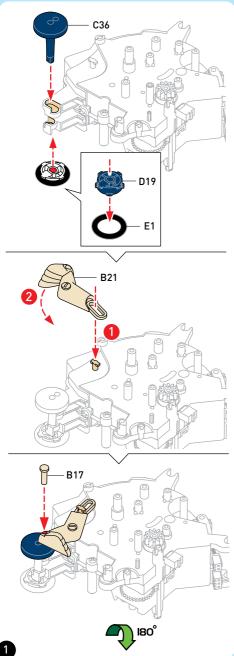


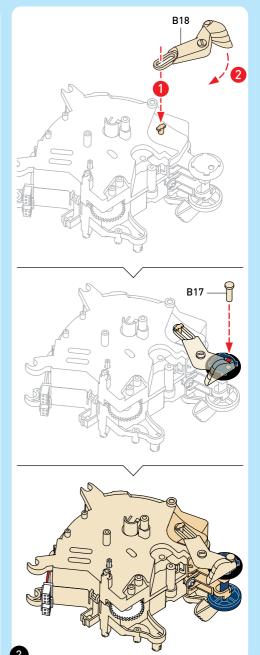


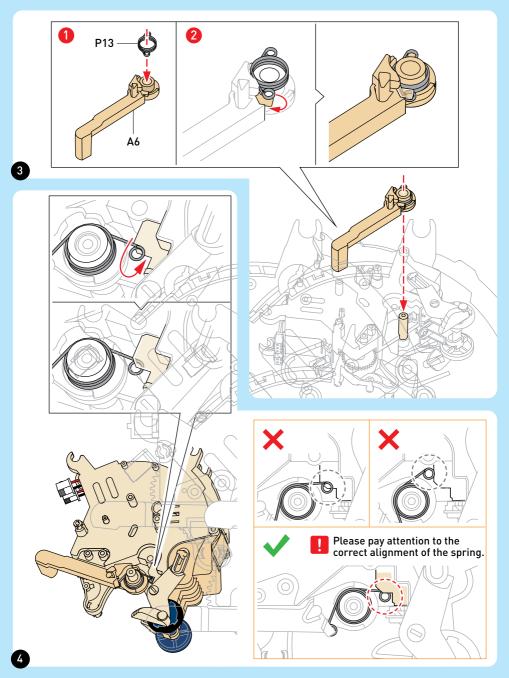


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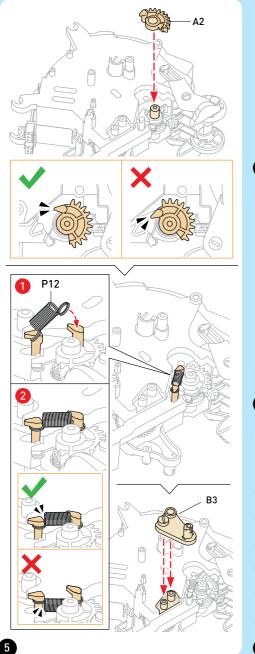


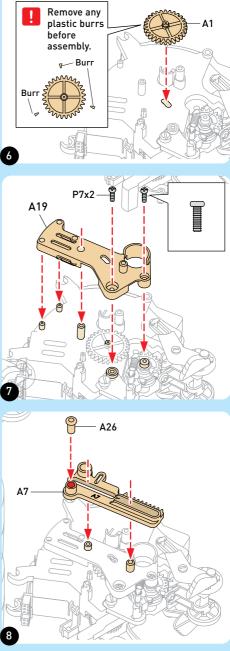


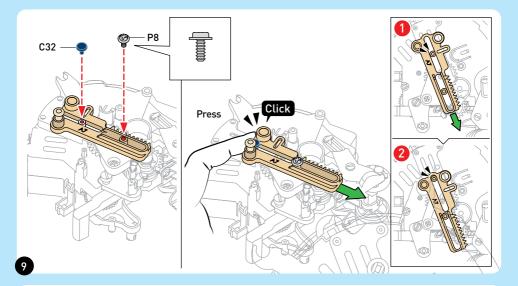


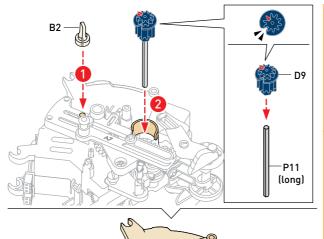


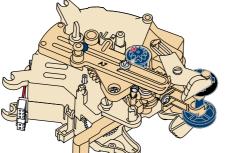
A1

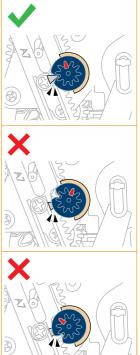






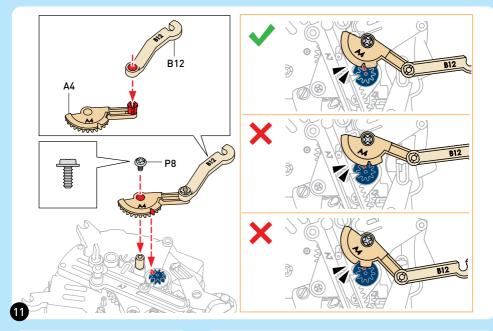


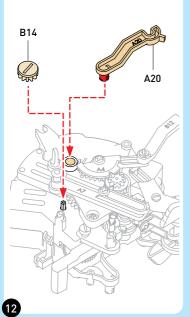


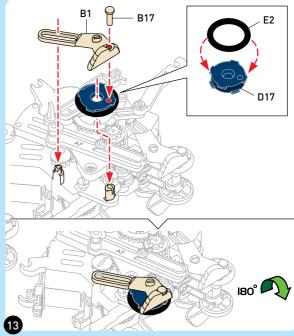


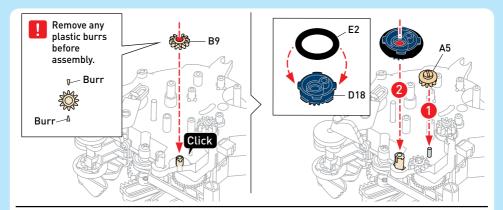
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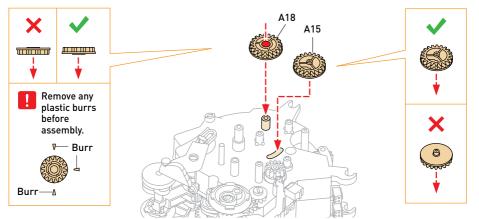
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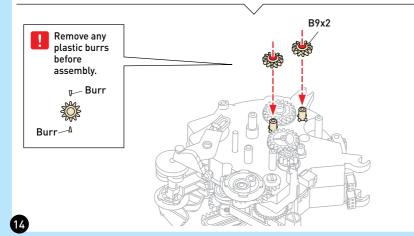


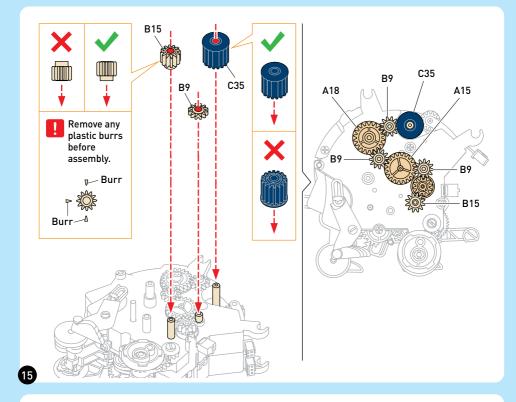


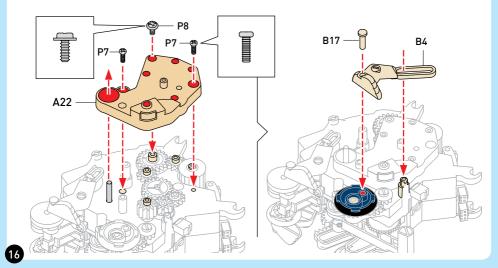


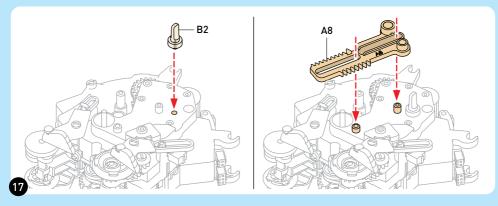


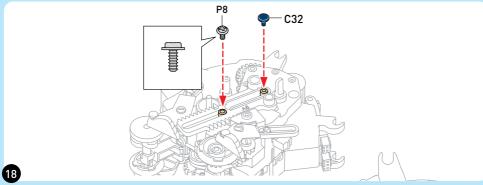


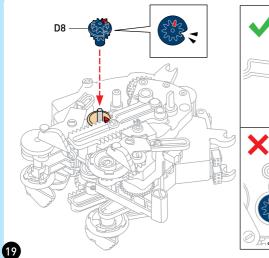


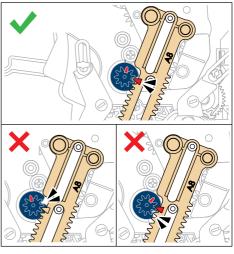


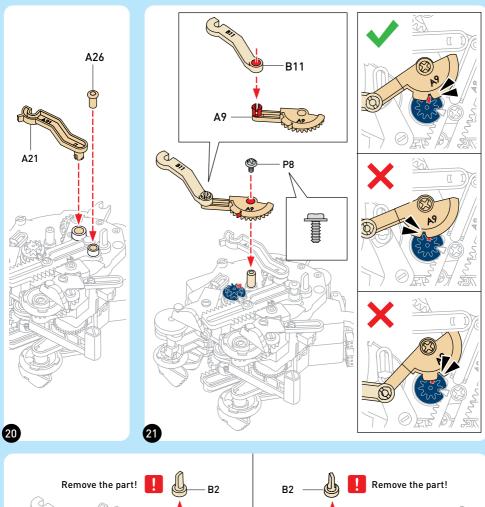


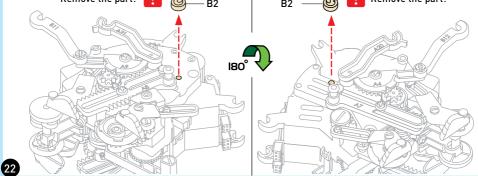


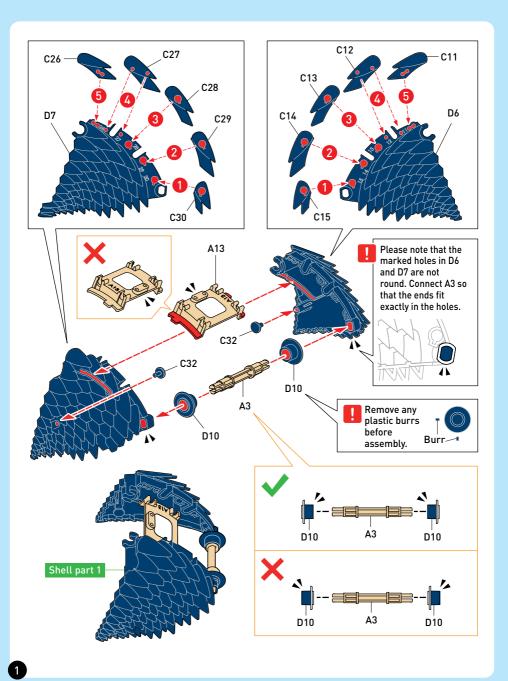




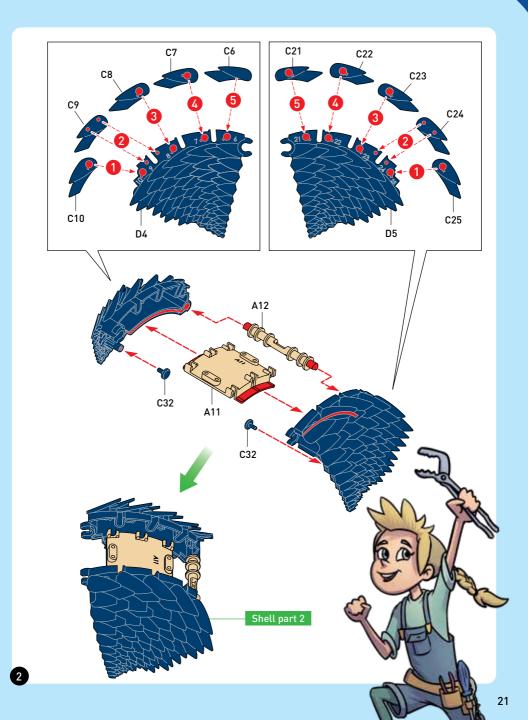




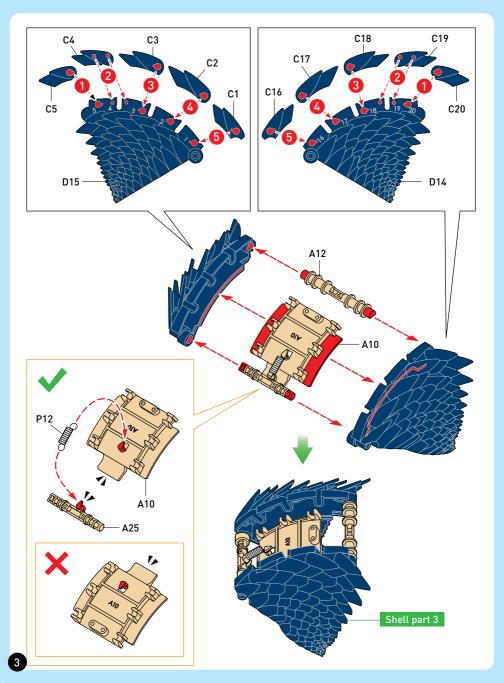


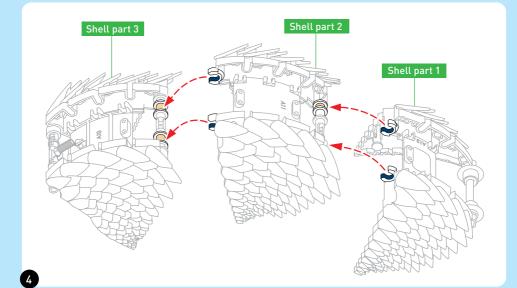


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OUTER SHELL









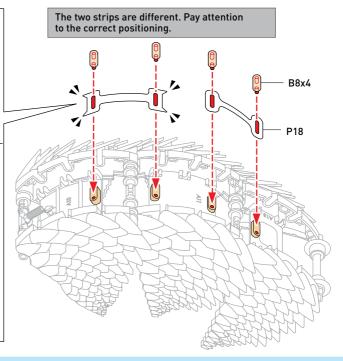
Carefully remove the plastic strips.

Careful!

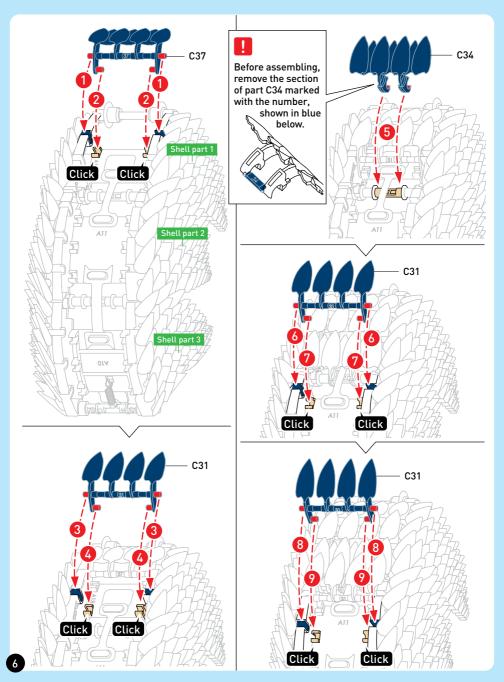
Make sure that the plastic strips are not folded or creased. Folded strips can lead to malfunctions.

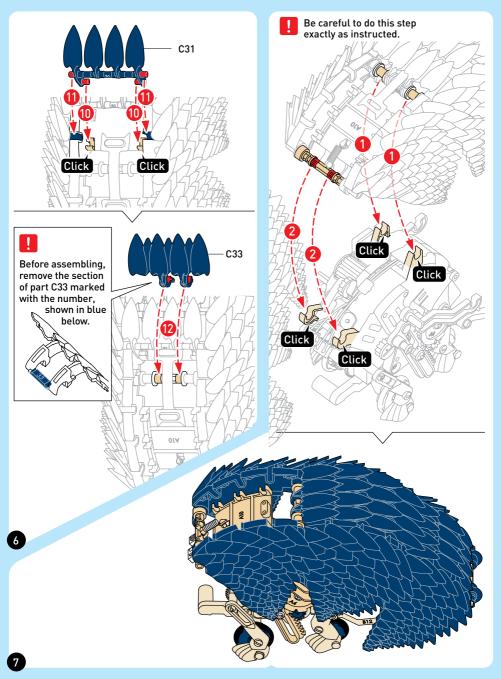




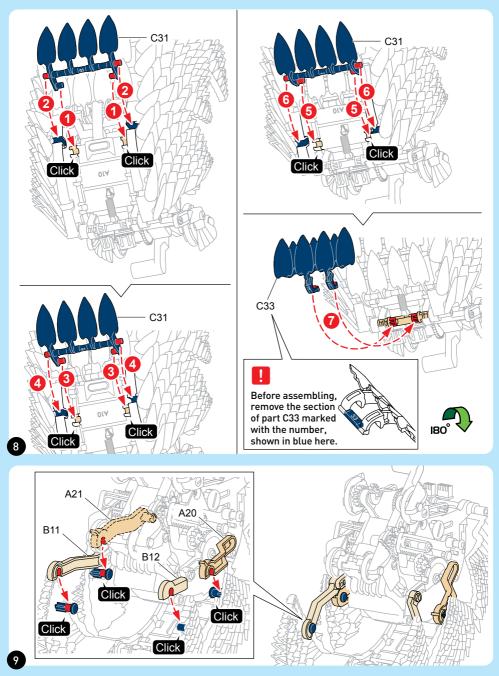


OUTER SHELL

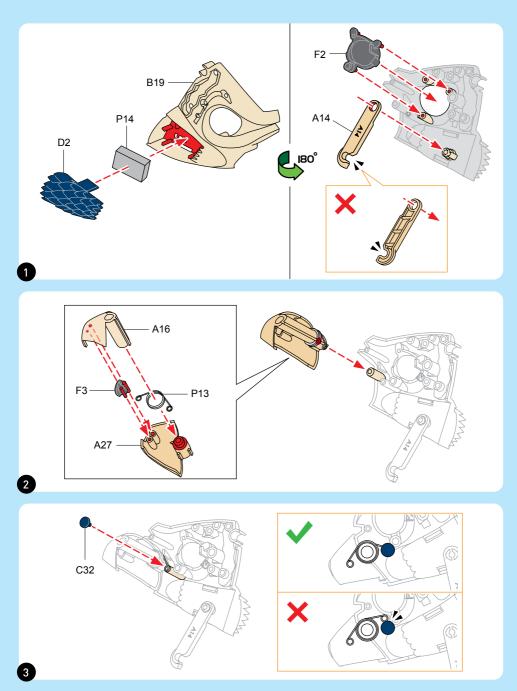


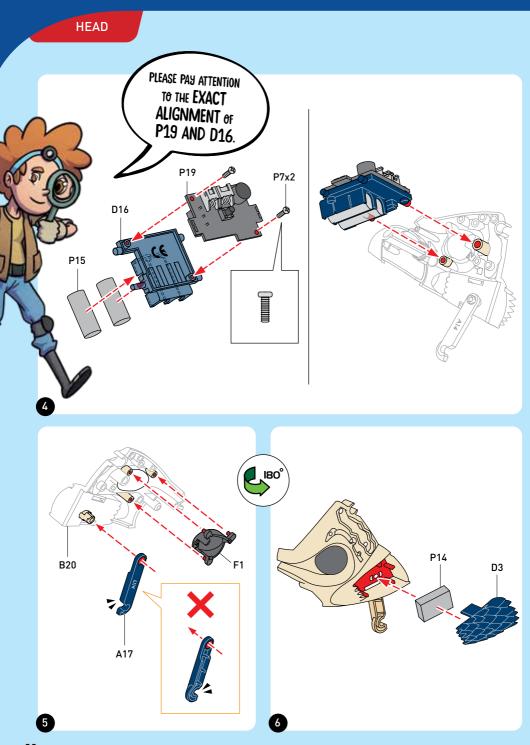


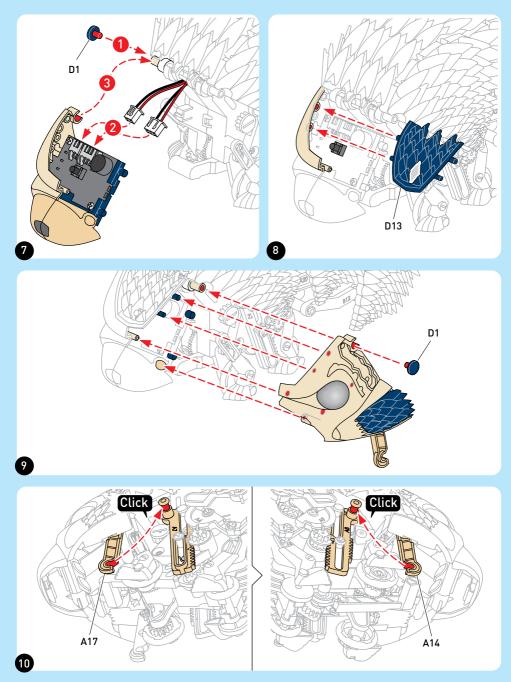
OUTER SHELL

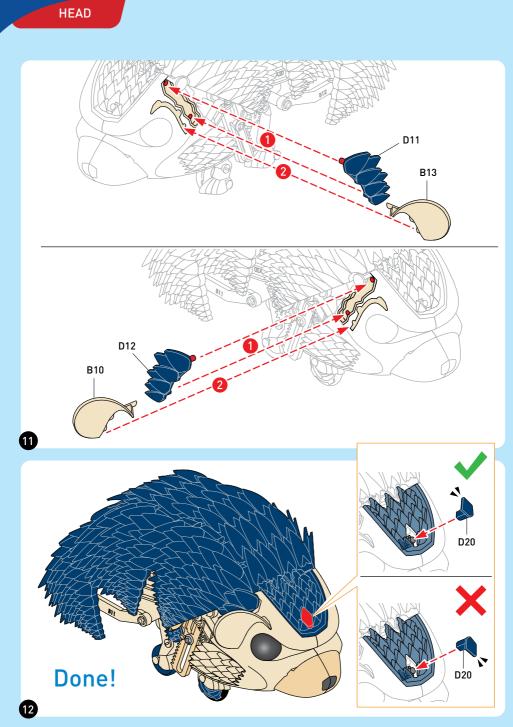


HEAD





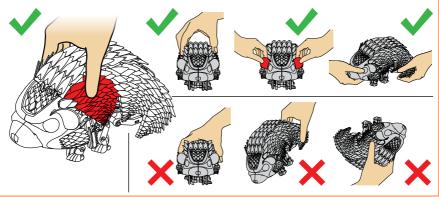




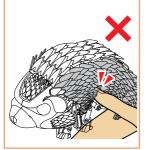
Appropriate care and handling

So that you may have fun with your robotic hedgehog for as long as possible, you should remember some things:

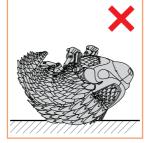
When you pick up the hedgehog, hold it as shown in the pictures.



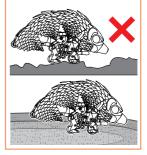
To avoid injury, never put your finger in the moving parts of the hedgehog. If the hedgehog curls up, it could trap your finger.



If the hedgehog ends up on its back, you have to turn it over again. When on its back, the hedgehog's eyes flash orange and green at the same time to alert you that it is in the wrong position.



The hedgehog works best on smooth surfaces. Your hedgehog robot will only be able to perform some of its functions (if any at all) on carpets or uneven floors.



1. Power on and standby mode

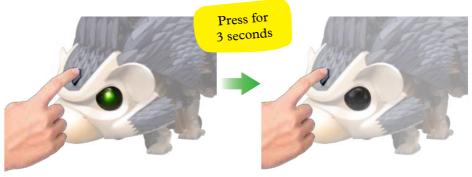
To turn your robotic hedgehog on, simply hold down the button on its forehead for two seconds. The hedgehog's eyes will then start to flash green. Now it is in standby mode and waiting for your next move.



The hedgehog is a little impatient. If you leave it waiting, it stamps its feet to remind you that it's waiting. If you let it wait for more than 60 seconds, it will automatically switch off again.

2. Turning off

You turn the hedgehog off the same way that you turned it on. This time, hold down the button for three seconds and the hedgehog shuts down and its eyes go dark.



SOUND SENSOR

Operating the Robot

The hedgehog robot can run like a real hedgehog and curl up. Fortunately, though, it listens to your orders and does not immediately start to curl up when you approach it.

You have given the hedgehog a built-in sound sensor, which is located on the circuit board in its head. You can use this sensor to control the hedgehog by giving orders by clapping.

Your hedgehog robot has three different modes. In each mode, you can give different clap commands.

Always make sure you clap close to its head where the sound sensor is located. If you're too far away or clapping too softly, the robot might not hear your commands properly.





IMPORTANT

The hedgehog robot only accepts orders when its body is completely stretched out. As soon as it curls up or if it is already curled up, the sound sensor is inactive and the robot will not follow your clap commands.





Mode 1: Roll backward and sleep

To activate mode 1, the hedgehog robot must be in standby mode. Now you just have to briefly press the button on its forehead and mode 1 is activated. The robot indicates that it is in this mode with its eyes glowing orange and green.

In mode 1, the robot can accept the following commands:





TIP!

Once the robot is turned on, you can cycle through the different modes by pushing the button on its forehead: Mode 1 \rightarrow Mode 2 \rightarrow Mode 3 \rightarrow Mode 1 \rightarrow and so on ... You can see which mode it is currently in by the colors that light up in its eyes.

Mode 2: Multiple backward rolls

When the robot is in standby mode, you activate mode 2 by pressing the button on its head twice. The robot indicates this mode with its eyes glowing green.

In mode 2, the robot can accept the following commands:



Command: 1x, 2x, 3x, 4x, or 5x claps

Function: The robot does as many backward rolls as you want (up to 5) — depending on how often you clap. It rolls in short intervals; that means it does a roll, unrolls, runs a little, and begins with the next roll.



Mode 3: Applauding for a backward roll

When the robot is in standby mode, you activate mode 3 by pressing the button on its head three times. The robot indicates this mode with its eyes glowing orange.

In mode 3, the robot can accept the following commands:



Command: Fast, consecutive clapping

Function: In this mode, the robot wants to be encouraged to move backward. Clap until it has done the roll. If you stop clapping beforehand, it will stretch out again and start walking.







REPLACING THE BATTERIES

Replacing the batteries with the body stretched out

Changing the batteries when the body is stretched out is in general a little easier. If you want to change the batteries while the body is stretched out, proceed as follows:

- Loosen the screw on the robot's underside (between the hind legs).
- Open the battery compartment cover by folding the flap and the back legs backward.

P8

• Pull out the battery compartment and change the batteries.

pet TIP!

If the robot is curled up and there is still some energy in the batteries, you can activate maintenance mode. In this mode, the body is stretched out and you can change the batteries as described. You activate the maintenance mode by keeping the button on the robot's head pressed for seven seconds.

Replacing the batteries with the body curled up

It could obviously happen that the batteries completely run out while the robot is curled up. In this case, you have to stretch the robot's body out by hand.

- Loosen clips A21 and B11.
- Loosen clips A20 and B12.
- Now you can manually stretch out the robot. This will help you get to the battery compartment and change the batteries as described above.
- You then have to refit the clips in their places.



Please observe the instructions for handling batteries on page 8.

FIND OUT HOW

TO CHANGE THE

BATTERIES

ON PAGE 38.

TROUBLESHOOTING

Troubleshooting

If the robot does not work as expected, check the following notes to detect and fix any problems.

- Make sure the batteries are inserted correctly. See page 8, step 3.
- 2. Make sure all cables are connected correctly. See page 29, step 7.
- 3. When the robot is on and lying on its back, its eyes flash green and orange to alert you that it is in the wrong position. Turn it over again and press the button on the head for 7 seconds, until the body stretches out and the lights in the eyes go out. Then you can press the button and again, hold for 2 seconds to restart the robot.
- 4. Should the robot's eyes flash green and orange after powering up for the first time (in standby mode), this means that it was put together incorrectly. If that happens, you should check the following steps:
 - Make sure that the part B2 has been removed. See page 19, step 22.
 - Make sure step 7 on page 25 has been done correctly.
 - Make sure all cables are connected correctly. See page 29, step 7.
- If the robot's spines do not stand up properly, make sure that you have correctly installed all movable spines. See pages 24 to 26, steps 6 to 8.
- If the lever on the robot's underside does not stand up correctly (in the reverse roll), you should make sure the steps 3 to 5 on pages 12 and 13 were performed correctly.
- 7. The following problems indicate batteries that are too weak:
 - The robot turns off automatically.
 - The robot does not respond when the button is pressed.
 - The robot goes into standby mode by itself.
 - The robot cannot curl up / unroll as usual.

REAL HEDGEHOGS

Hedgehogs are fascinating animals that are found in many parts of the word, including Europe, Asia, Africa, and New Zealand. They are not found in the wild in America or Australia.

Your hedgehog robot has quite a few spines. However, a true, full-grown hedgehog has up to 9,000 spines, each of which is sharper than a pin.

Like your robotic hedgehog, real hedgehogs curl up into a ball. But only if they feel threatened. They will then roll up so tightly that their delicate undersides are almost invisible. By doing so, they are well protected against attackers.



WHAT IS BIONICS?



Bionics is when natural phenomena or amazing things from nature are transferred to technology. People copy what you could call tricks right out of nature. A good example of this is the invention of Velcro. The technique for it came from a plant called burdock. The flowers of this plant have fine hooks that get caught in our clothes or in the fur of our pets. Velcro works on the same principle.

The robotic hedgehog was also designed to mimic its natural model, the hedgehog. In that way, it is a bionic robot.

Close up of Velcro



Kosmos Quality and Safety

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Photos instructions: picsfive (all push pins); askaja (all paper clips); Jaimie Duplass (all adhesive tapes); Matt Bianco, p. 40 o; Suzanne Tucker, p. 40 m; Cristan Ritchie, p. 40 &; (all prior © shutterstock.com)

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(1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

